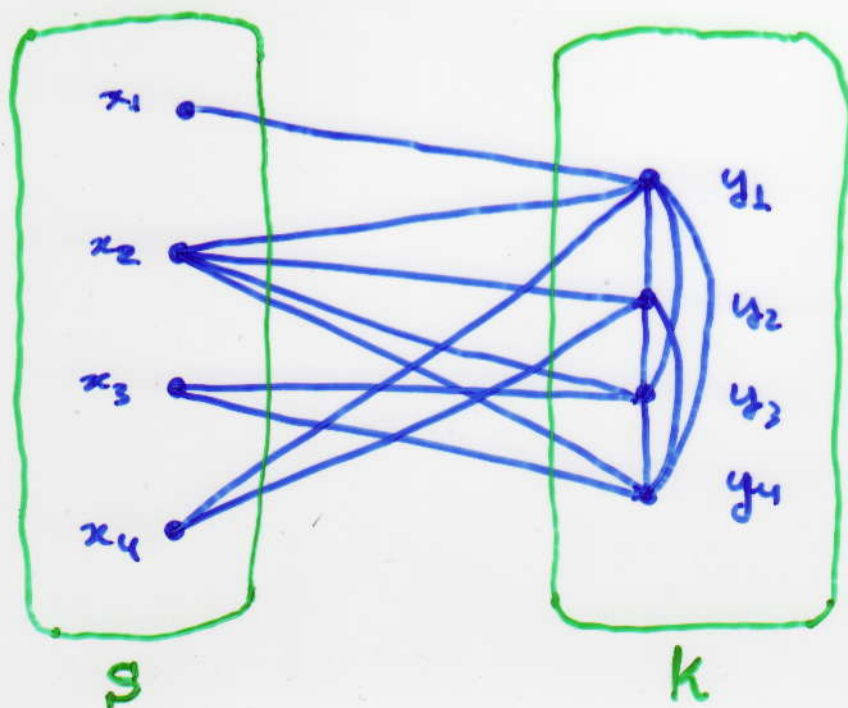
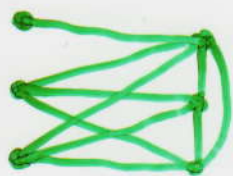


① Split Graphs

- An undirected graph $G=(V,E)$ is defined to be **split** if there is a partition $V=S+K$ of its vertex set:
 S = stable set and K = complete set.
- In general, the partition $V=S+K$ of a split graph will not be unique.
- S will not necessarily be a maximal stable set.
 K \Rightarrow K \Rightarrow maximal clique.



- Since a stable set of G is a complete set of \bar{G} and vice versa, we have an immediate result.
- **Theorem:** G is a split graph iff \bar{G} is a split graph.
- The next theorem follows from the work of Hammer and Simeone [1977].
- **Theorem:** Let G be a split graph and $V = S + K$. Exactly one of the following conditions holds:
 - (i) $|S| = \alpha(G)$ and $|K| = \omega(G)$
 - (ii) $|S| = \alpha(G)$ and $|K| = \omega(G) - 1$
 - (iii) $|S| = \alpha(G) - 1$ and $|K| = \omega(G)$



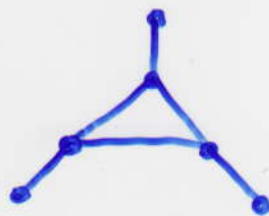
• **Theorem** (Földes and Hammer [1977]).

Let G be an undirected graph. The following conditions are equivalent:

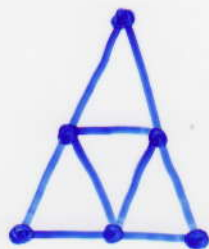
- (i) G is a split graph;
- (ii) G and \bar{G} are triangulated graphs;
- (iii) G contains no induced subgraph $\cong 2K_2, C_4, C_5$

• A characterization of when a split graph is also a comparability graph is given by the following theorem:

• **Theorem:** If G is a split graph, then G is a comparability graph iff G contains no induced subgraph isomorphic to H_1, H_2 or H_3



H_1



H_2



H_3

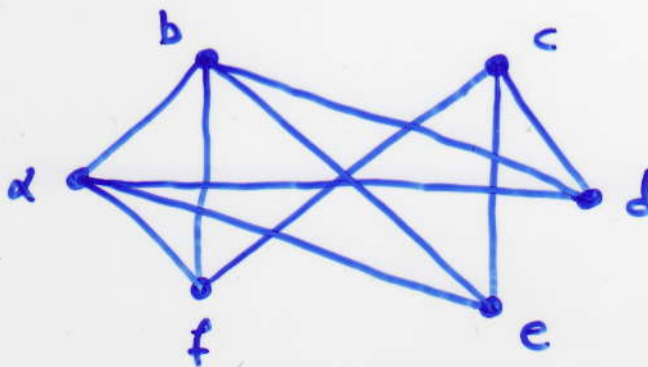
● Cographs (or Complement reducible graphs)

● **Cographs** are defined as the class of graphs formed from a single vertex under the closure of the operations of **union** and **complement**.

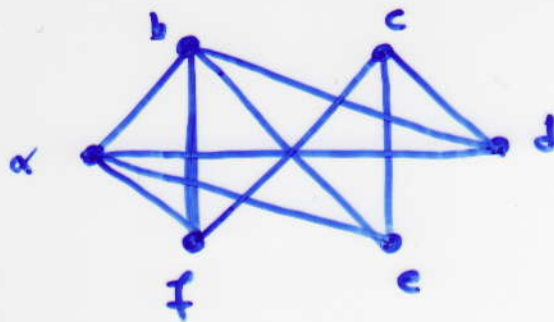
● More precisely, the class of cographs can be defined recursively as follows:

- (i) a single-vertex graph is a **cograph**;
- (ii) the disjoint union of a cograph is a **cograph**;
- (iii) the complement of a cograph is a **cograph**;

● **Example:**



• Construction of the following cograph:



U: $\bullet^a + \bullet^b$



cograph

C: $\bullet^a \bullet^b$



\Rightarrow

U: $\bullet^a \bullet^b + \bullet^c$



\Rightarrow

C: $\bullet^a \bullet^b \bullet^c$



\Rightarrow

U: $\bullet^d + \bullet^e + \bullet^f$



\Rightarrow

C: $\bullet^d \bullet^e \bullet^f$

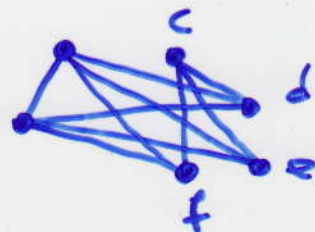


\Rightarrow

U: $\bullet^a \bullet^b \bullet^c + \bullet^d \bullet^e \bullet^f$



C:



\Rightarrow

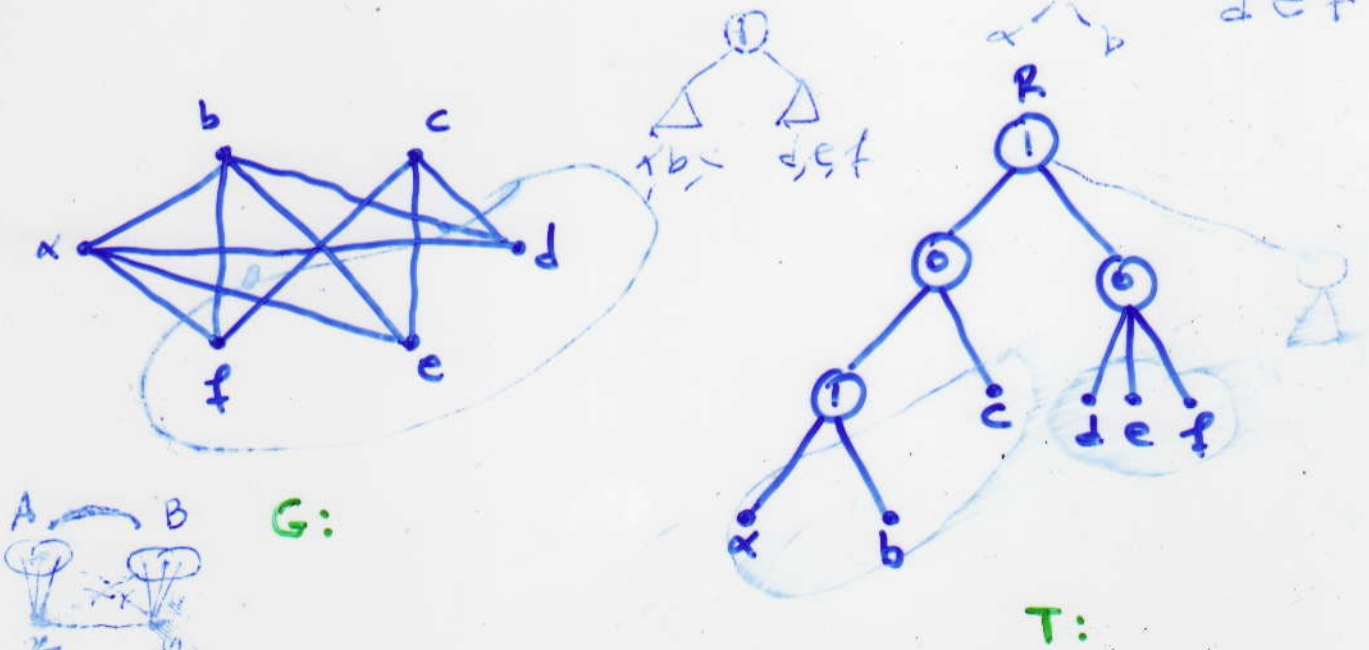
- Cographs were introduced in the early 1970s by Lerchs.

- Lerchs has shown, among other properties, the following two very nice algorithmic properties:

(P1) cographs are exactly the P_4 restricted graphs

(P2) cographs have a unique tree representation called cotree.

• A cograph and its cotree:



- The root R will have only one (0) node child iff the represented cograph is disconnected.

⊙ Permutation Representation of a Cograph

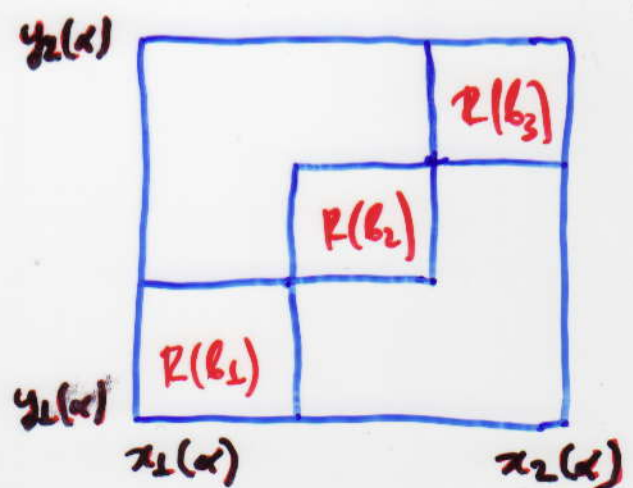
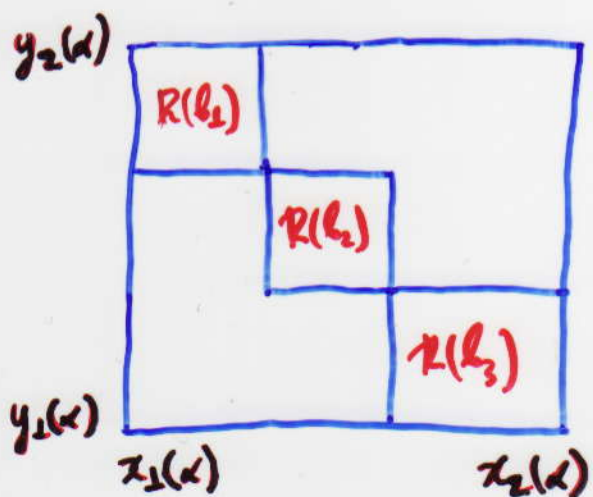
- Let G be a cograph with cotree T .
- We plot the vertices of G on an $n \times n$ grid.
- For each node $\alpha \in T$, we denote:
 - $G(\alpha)$ the subgraph $G[L(T(\alpha))]$.
 - $L(T(\alpha))$ the set of the leaf nodes in $T(\alpha)$.
 - $T(\alpha)$ the subtree of T rooted at α .
- The vertices of $G(\alpha)$ will be plotted on a $u(\alpha) \times u(\alpha)$ square region $R(\alpha)$ on the grid, where $u(\alpha)$ is the number of vertices in $G(\alpha)$.
- We represent

$$R(\alpha) = [x_1(\alpha), y_1(\alpha), x_2(\alpha), y_2(\alpha)]$$

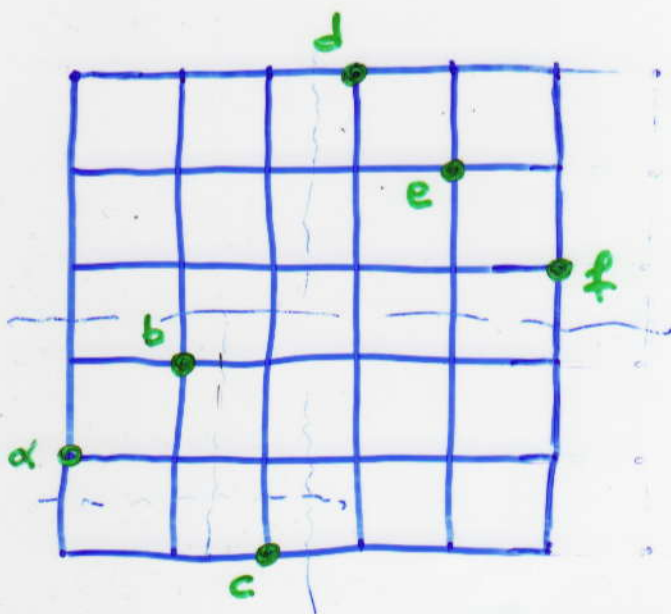
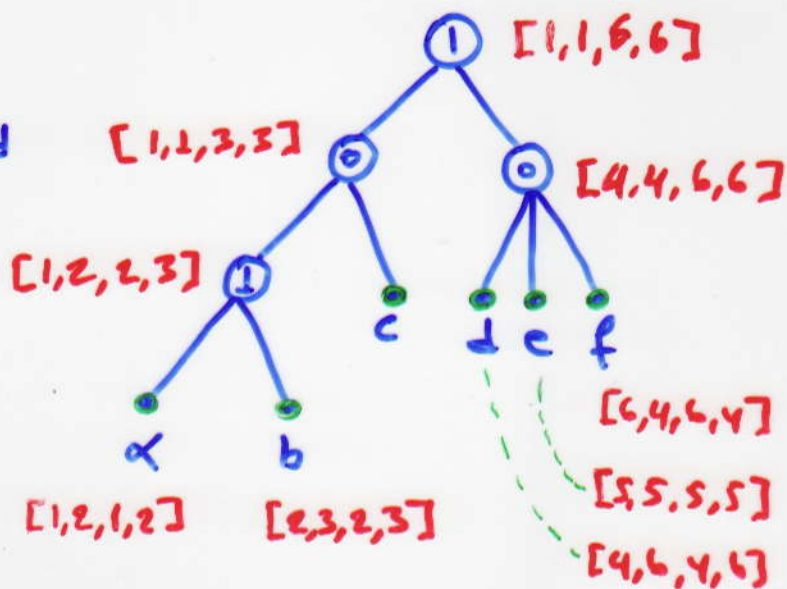
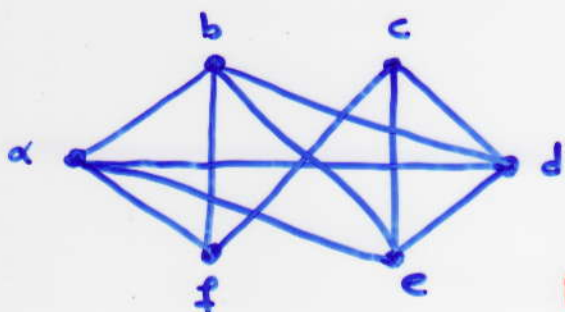
where

$(x_1(\alpha), y_1(\alpha))$ is the lower-left corner, and
 $(x_2(\alpha), y_2(\alpha))$ is the upper-right corner.

- Our algorithm is a top-down computation on T .
- For the root r of T , let $R(r) = [l, l, n, n]$.
- Consider an internal node α with children b_1, b_2, \dots, b_k .
- Suppose $R(\alpha) = [x_1(\alpha), y_1(\alpha), x_2(\alpha), y_2(\alpha)]$ has been computed, we describe how to compute $R(b_i) = [x_1(b_i), y_1(b_i), x_2(b_i), y_2(b_i)]$ for each $1 \leq i \leq k$.
- Case 1: α is a 0-node
- Case 2: α is a 1-node



• Example :



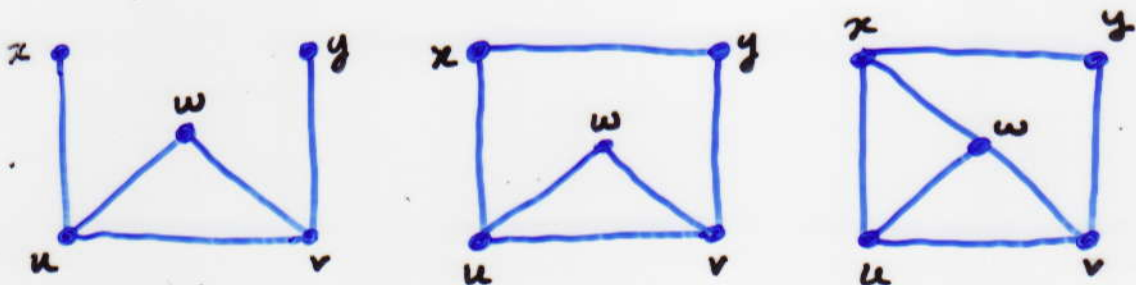
$$\pi = [2, 3, 1, 6, 5, 4]$$

Recognition Properties of Cograph

• **Theorem:** Let G be a graph. The following statements are equivalent:

- (i) G is a cograph;
- (ii) G does not contain P_4 as a subgraph;

• **Example:**



• For every actual edge $(x, y) \in E$ we define:

$$AV_{(x,y)}^x = \{z \in V \mid (x, z) \in E \text{ and } (y, z) \notin E\}$$

$$AV_{(x,y)}^y = \{z \in V \mid (x, z) \notin E \text{ and } (y, z) \in E\}$$

• For every pair $x, y \in V$: $(x, y) \notin E$ we define:

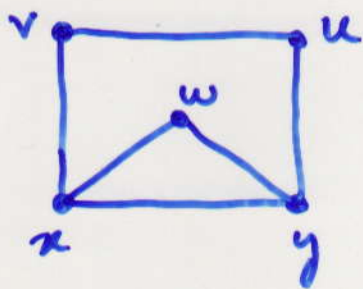
$$FV_{\{x,y\}} = \{z \in V \mid (x, z) \in E \text{ and } (y, z) \in E\}$$

• **Theorem:** Let $G=(V,E)$ be an A -free graph. Then, G is a cograph.

• **Theorem:** Let $G=(V,E)$ be a graph. The following statements are equivalent:

- (i) G is a cograph;
- (ii) There exists no actual edge $(x,y) \in AE$ and vertices $v \in AV_{(x,y)}^x$, $u \in AV_{(x,y)}^y$ such that either $N(v) \cup N(y) \neq FV_{\{v,y\}}$ or $N(u) \cup N(x) \neq FV_{\{u,x\}}$.

• **Example:**



1) $(x,y) \in AE$

$$N(v) \cup N(y) = \{x, u\}$$

$$FV_{\{v,y\}} = \{x, u\}$$

$$N(u) \cup N(x) = \{v, y\}$$

$$FV_{\{u,x\}} = \{v, y\}$$

2) $(v,x) \in AE$

$$N(u) \cup N(x) = \{v, w, y\}$$

$$FV_{\{u,x\}} = \{v, y\}$$

$\Rightarrow G$ is not a cograph.

• Algorithm Recognition - Cographs

1. For every $(x, y) \in AE$ do
1.1. compute $AV_{(x,y)}^x$ and $AV_{(x,y)}^y$;

2. For every pair $x, y \in V$: $(x, y) \notin E$ do
2.1. compute $FV_{\{x,y\}}$;

3. For every actual edge $(x, y) \in AE$ do

3.1. for every vertex $v \in AV_{(x,y)}^x$ do
if $N(v) \cup N(y) \neq FV_{\{x,y\}}$ then P_4 ; stop;

3.2. for every vertex $u \in AV_{(x,y)}^y$ do
if $N(u) \cup N(x) \neq FV_{\{x,y\}}$ then P_4 ; stop;

end.

• The algorithm runs in $O(\delta \cdot m)$ where δ is the degree of the input graph.

• The algorithm can be implemented in $O(1)$ time with $O(\delta \cdot m)$ processors on a $CRCW$ -PRAM.

⊙ Threshold Graphs

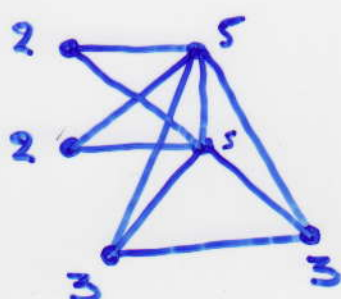
- Chvátal and Hammer have proved the following result:
- **Theorem:** Let $G=(V,E)$ be a graph. The following statements are equivalent:
 - (i) G is a threshold graph; $\square \square \square \parallel$
 - (ii) G has no induced subgraphs \cong to P_4, C_4 or $2K_2$
- There exist an $O(n)$ -time sequential algorithm for recognizing threshold graphs.
- The algorithm is based on the **degree partition**.
- Let $\delta(v)$ be the degree of the vertex v of an undirected graph.

- We define the degree partition of a graph $G=(V,E)$ in which we associate vertices having the same degree.
- Let $0 < \delta_1 < \delta_2 < \dots < \delta_k < |V|$ be the degrees of the nonisolated vertices.
- δ_i are distinct; there may be many vertices of degree δ_i .
- Define: $\delta_0 = 0$ and $\delta_{k+1} = |V| - 1$
- The degree partition of V is given by

$$V = D_0 + D_1 + \dots + D_k$$

where $D_i =$ set of all vertices of degree δ_i .

• Example:



$$\delta_1 = 2$$

$$\delta_2 = 3$$

$$\delta_3 = 5$$

$$0 < \delta_1 < \delta_2 < \delta_3 < 6$$

• The main idea of the recognition Algorithm:

(a) First, it brings together all vertices with the same degree.

(b) The vertex set V is partitioned into $k+1$ disjoint vertex sets

$$V = D_0 + D_1 + \dots + D_k$$

satisfying the property

$$u \in D_i \iff \delta(u) = i$$

$$0 \leq i \leq k.$$

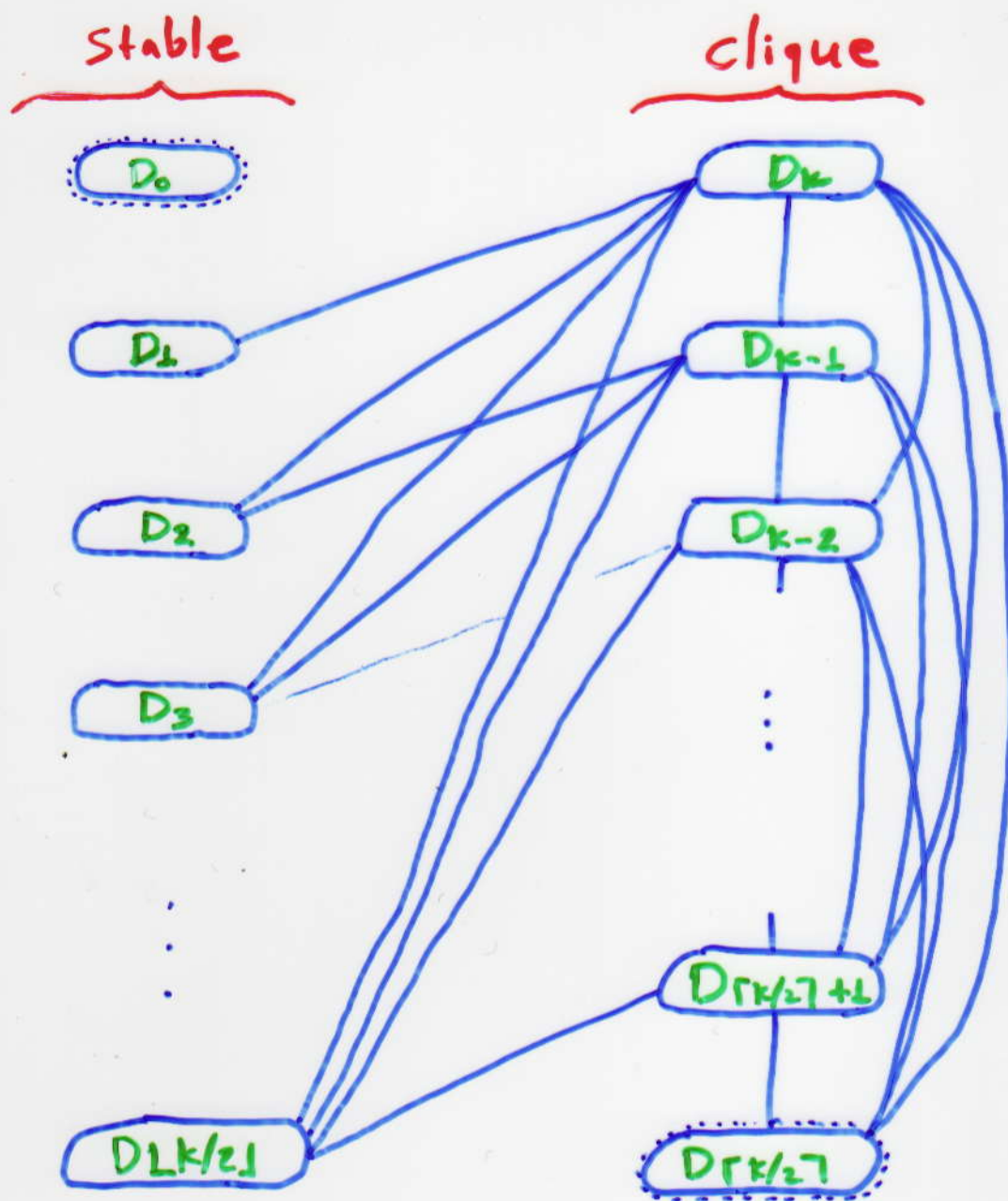
(c) Then, the algorithm uses the following result:

G is a threshold graph iff the recursions below are satisfied:

$$\delta_{i+1} = \delta_i + |D_{k-i}| \quad (i=0, 1, \dots, \lfloor k/2 \rfloor - 1)$$

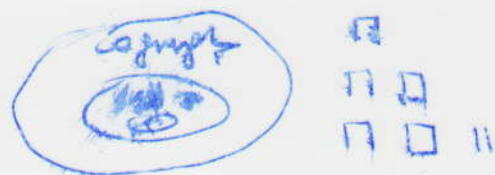
$$\delta_i = \delta_{i+1} + |D_{k-i}| \quad (i=k, k-1, \dots, \lfloor k/2 \rfloor + 1)$$

- The typical structure of a threshold graph:



- D_0 contains all isolated vertices (may be empty).
- $D_{\lfloor k/2 \rfloor}$ only exists if k is odd
- $\delta_0 = 0$ and $\delta_{k+1} = |V| - 1$

① A-free Graphs



- A graph $G=(V,E)$ is called an **A-free graph** if every edge of G is either **free** or **semi-free**.



- We define

$$\text{cent}(G) = \{x \in V \mid N[x] = V\}$$

- **Theorem:** Let G be a graph. Then the following statements are equivalent:
 - (i) G is a **A-free graph**;
 - (ii) G has no induced subgraph \cong to P_4 or C_4 ;
 - (iii) Every connected induced subgraph $G[S]$, $S \subseteq V$, satisfies $\text{cent}(G[S]) \neq \emptyset$.
- **Lemma:** The following two statements hold:
 - (i) G is an **A-free** iff $G - \text{cent}(G)$ is an **A-free**;
 - (ii) If $G - \text{cent}(G) \neq \emptyset$, then $G - \text{cent}(G)$ contains at least two components.

- Let G be an A -free graph. Then,

$$V_1 = \text{cent}(G).$$

- Put $G_1 = G$

$$G - V_1 = G_2 \cup G_3 \cup \dots \cup G_r$$

where

G_i is a component of $G - V_1$, $r \geq 2$.

- Then, G_i is an A -free graph, and so

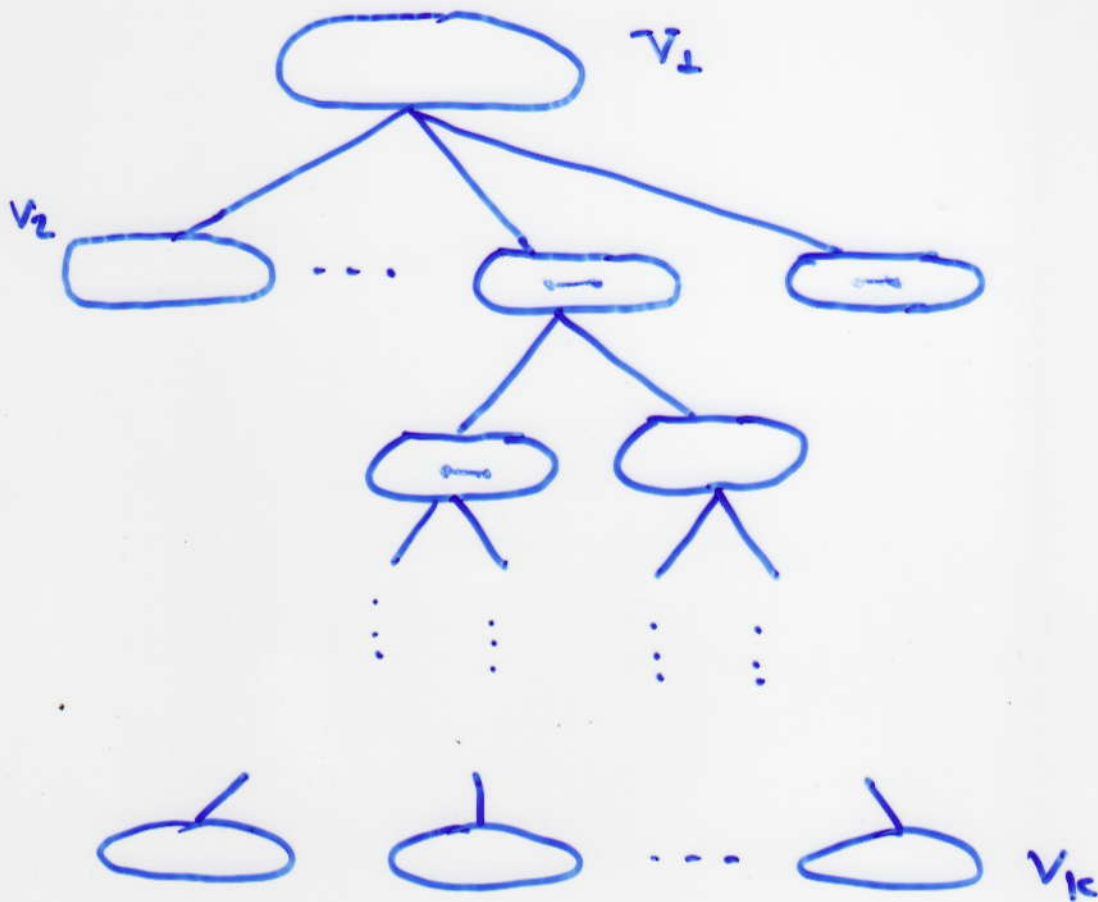
$$V_i = \text{cent}(G_i) \neq \emptyset$$

- We finally obtain the following partition of V :

$$V = V_1 + V_2 + \dots + V_k$$

where $V_i = \text{cent}(G_i)$.

- The typical structure of an A-tree graph:



- Moreover we can define a partial order \leq on $\{v_1, v_2, \dots, v_k\}$ as follows:

$$v_i \leq v_j \text{ if } v_i = \text{cent}(G_i) \text{ and } v_j \in V(G_i).$$

- Let G be a connected A -free graph, and let $V(G) = V_1 + V_2 + \dots + V_k$ be the partition defined above.

Then this partition and the partially ordered set $(\{V_i\}, \leq)$ have the following properties:

- (P1) If $V_i \leq V_j$ then every vertex of V_i and every vertex of V_j are joined by an edge.
- (P2) For every V_i , $\text{cent}(G[\{ \cup V_i \mid V_i \leq V_j \}]) = V_i$.
- (P3) For every two V_s and $V_t : V_s \leq V_t$, $G[\{ \cup V_i \mid V_s \leq V_i \leq V_t \}]$ is a complete graph. Moreover, for every maximal element V_t of $(\{V_i\}, \leq)$, $G[\{ \cup V_i \mid V_1 \leq V_i \leq V_t \}]$ is a maximal complete subgraph of G .
- (P4) Every edge $(x, y) : x, y \in V_i, (x, y) \in FE;$
 " " : $x \in V_i, y \in V_j, V_i \neq V_j,$
 $(x, y) \in SE;$

- G is a threshold graph iff G has no induced subgraphs isomorphic to C_4 , P_4 or $2K_2$.
- **Theorem:** The threshold graphs are precisely those A -free graphs containing no induced subgraph isomorphic to $2K_2$.
- **Theorem:** Let G be an A -free graph. The following statements are equivalent:
 - G contains no $2K_2$;
 - \bar{G} is an A -free graph;

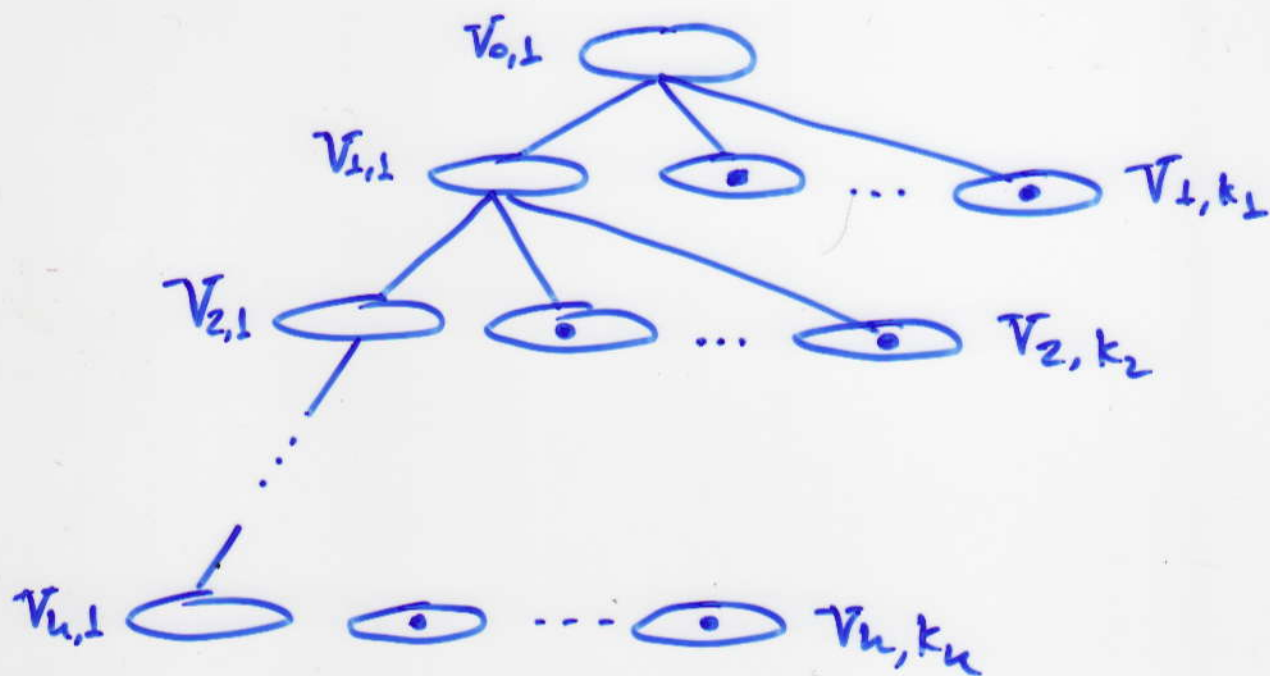
Proof. (i) \Rightarrow (ii): Let $T_c(G)$ be the cent-tree of G and let $V_{1,1}, V_{1,2}, \dots, V_{1,k_1}$ be the children of the node $V_{0,1} = \text{cent}(G)$;



Then, \exists at least one child of $V_{0,1}$: $|V_{1,1}| \geq 1$.

son

We can only prove that the typical structure of an A -free graph which contains no induced subgraph \cong to $2k_2$ is the following:



The cent-tree has the following properties:

- (P1) $K = V_{0,1} \cup V_{1,1} \cup \dots \cup V_{h,1}$ is a clique
- (P2) $S = V - K$ is an independent set.
- (P3) For every $x, y \in S$: $\text{level}(x) < \text{level}(y)$,
 $N(x) \subseteq N(y)$.

We can only prove that \bar{G} is an A -free graph.

(ii) \Rightarrow (i): Suppose G contains $2k_2$. Then, \bar{G} contains C_4 , a contradiction.

• **Theorem:** Let $G=(V,E)$ be an undirected graph. The following statements are equivalent:

(i) G is a threshold graph;

(ii) G and \bar{G} are A -free graphs;

• The free, semi-free and actual vertices of a connected graph G with n vertices and m edges can be computed in $O(S \cdot m)$ time.

• Thus, threshold graphs can be recognized in $O(S \cdot m + n^2)$ time.

• A -free, cographs and threshold graphs can be recognized in $O(1)$ time by using $O(n \cdot m)$ processors on a CRCW-PRAM

or

in $O(\log n)$ time by using $O(n \cdot m / \log n)$ processors.